

Learning Manifold Patch-Based Representations of Man-Made Shapes

SUMMARY

We propose a fully self-supervised method for learning a patch-based representation of piecewise-smooth manifold 3D geometry. This representation is sparse, interpretable, and easily editable, making it a convenient choice for downstream tasks in design and modeling.

DEFORMABLE PATCH-BASED REPRESENTATION

Our network directly outputs control points that define a P(0, t) collection of CAD parametric patches (right). The topology P(0,0) and rough geometry of these patches are defined by a deformable template, which automatically generate per shape category (below).





PIPELINE OVERVIEW



CAD MODEL EDITING



Because we output 3D geometry as a collection of consistent, well-placed NURBS patches, user edits can be made in conventional CAD software by simply moving control points. Here, we are able to refine the trunk of a car model with just a few clicks.

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 $P\colon [0,1]^2 \to \mathbb{R}^3$ $P(s,t) = \sum a_{i,j} s^i t^j$

Sampling uniformly in parameter space, uniform with respect to surface area.

$$f(P) = \frac{1}{\operatorname{Area}(P)} \int_{P} d(x) dx$$
$$= \frac{1}{\operatorname{Area}(P)} \int_{0}^{1} \int_{0}^{1} d(P(s,t)) |J$$

DATA GENERATION





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PROJECT WEBPAGE http://people.csail.mit.edu/smirnov/learning-patches/

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